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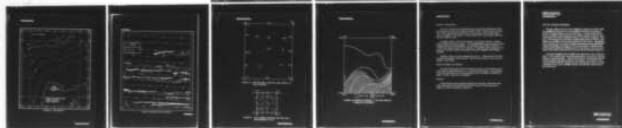
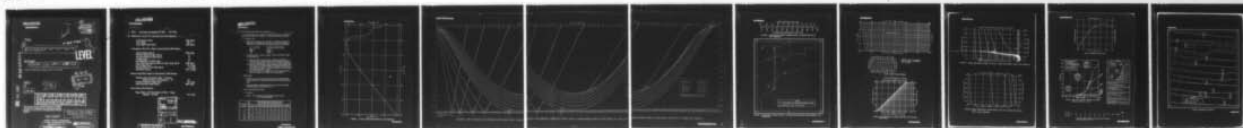
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OCEANOGRAPHY FOR LONG RANGE SONAR IN ATLANTIC AREA B FOR FEBRUA--ETC(U)
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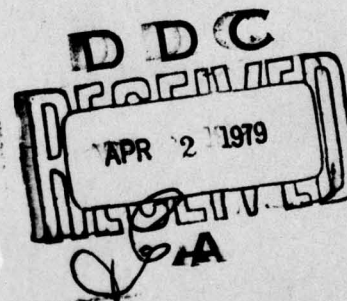
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OCEANOGRAPHY FOR LONG RANGE SONAR IN ATLANTIC
AREA B FOR FEBRUARY

LEVEL

AUTHOR

14 NOO-IM-0-104-63

OCEANOGRAPHIC DEVELOPMENT DIVISION



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Abstract

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CONTENTS:

- 1 - AREA: One-degree quadrangle 25°-26°N 72°-73°W;
2 - PREDICTED VALUES FOR QUADRANGLE FOR FEBRUARY; and

Sound Speed at Sonar	5026 ft/sec
Layer Depth	250 ft
Layer Depth Sound Speed	5030 ft/sec

Convergence Zone (For a depth of approximately 2900 fathoms)

Speed at Bottom (Fig 4)	5090 ft/sec
Minimum Refracted Angle (Fig 6)	2°
Maximum Refracted Angle (Fig 6)	9°
Average Angle	5°
Best Equipment Tilt (D/E) Angle	5°
Mean Horizontal Speed for Best Tilt (D/E) Angle (Fig 8)	4920 ft/sec
Initial Range (Fig 7)	70.0 kyds
Reswept Surface Zone Width (Fig 2)	2.0 kyds
Slant Path Velocity	4961.5 ft/sec

Bottom Bounce (For a depth of approximately 2900 fathoms)

Minimum useful Inclination Angle = Maximum Refracted Angle of Convergence + 3° =	12°
Predicted Detection Range (Fig 7)	50.0 kyds
Mean Horizontal Speed (Fig 8)	4860 ft/sec

Near Surface Path Detection

Range (Table I) (12-Knot Figure of Merit + Target Strength = 215 db)	37.0 kyds
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III USE OF GRAPHS FOR PARTICULAR CONDITIONS

← ABSTRACT

1. From BT temperature trace, determine and tabulate sound speed at sonar depth (V_1) and at layer depth (V_2) from Figure 5. Tabulate bottom (V_3) from Figure 4.

2. Convergence zone

a. Determine if convergence zone is possible. The difference between the bottom speed (V_3) and speed at sonar depth (V_1) will give a qualitative indication of convergence zone existence according to the table below.

$V_3 - V_1$ (ft/sec)	Convergence Zone Existence
Negative	None
0-30	Borderline
>30	Strong

b. To determine angular width and midpoint of totally refracted rays usable in convergence zone:

- (1) Determine minimum angle for totally refracted ray from Figure 6 using sound speed at sonar depth (V_1) and sound speed at layer depth (V_2) (first vertexing speed). With no layer, the minimum angle is 0° .
- (2) Determine maximum angle for totally refracted ray from Figure 6 using sound speed at sonar depth and bottom sound speed (V_3) (second vertexing speed) from Figure 4. (Bottom sound speed may also be obtained from sound speed profile in Figure 1).
- (3) Best tilt (D/E) angle for convergence zone will be that equipment tilt nearest the average of the minimum and maximum angles.

3. Bottom Bounce

- a. Refracted ray angle (to the nearest degree) tangent to the bottom [Item 2 b (2), above] plus 3° determines the minimum useful bottom bounce Ray angle.
- b. Use the equipment tilt (D/E) angle nearest to the minimum useful bottom bounce Ray angle as computed in Item III 3 a.

4. Near surface path detection range

a. Use Table 1.

TABLE 1 MEAN SURFACE PATH DETECTION RANGE (KYDS)
OF A SHALLOW TARGET

LAYER DEPTH (FEET)	FIGURE OF MERIT PLUS TARGET STRENGTH (ALLOWABLE TWO-WAY LOSS IN DB)										
	170	175	180	185	190	195	200	205	210	215	220
0	3	3	4	4	5	5	6	7	8	8	9
50	7	8	10	11	12	14	15	17	19	20	22
100	10	11	13	16	17	19	22	24	26	29	31
400	13	17	19	23	27	30	34	38	41	45	49

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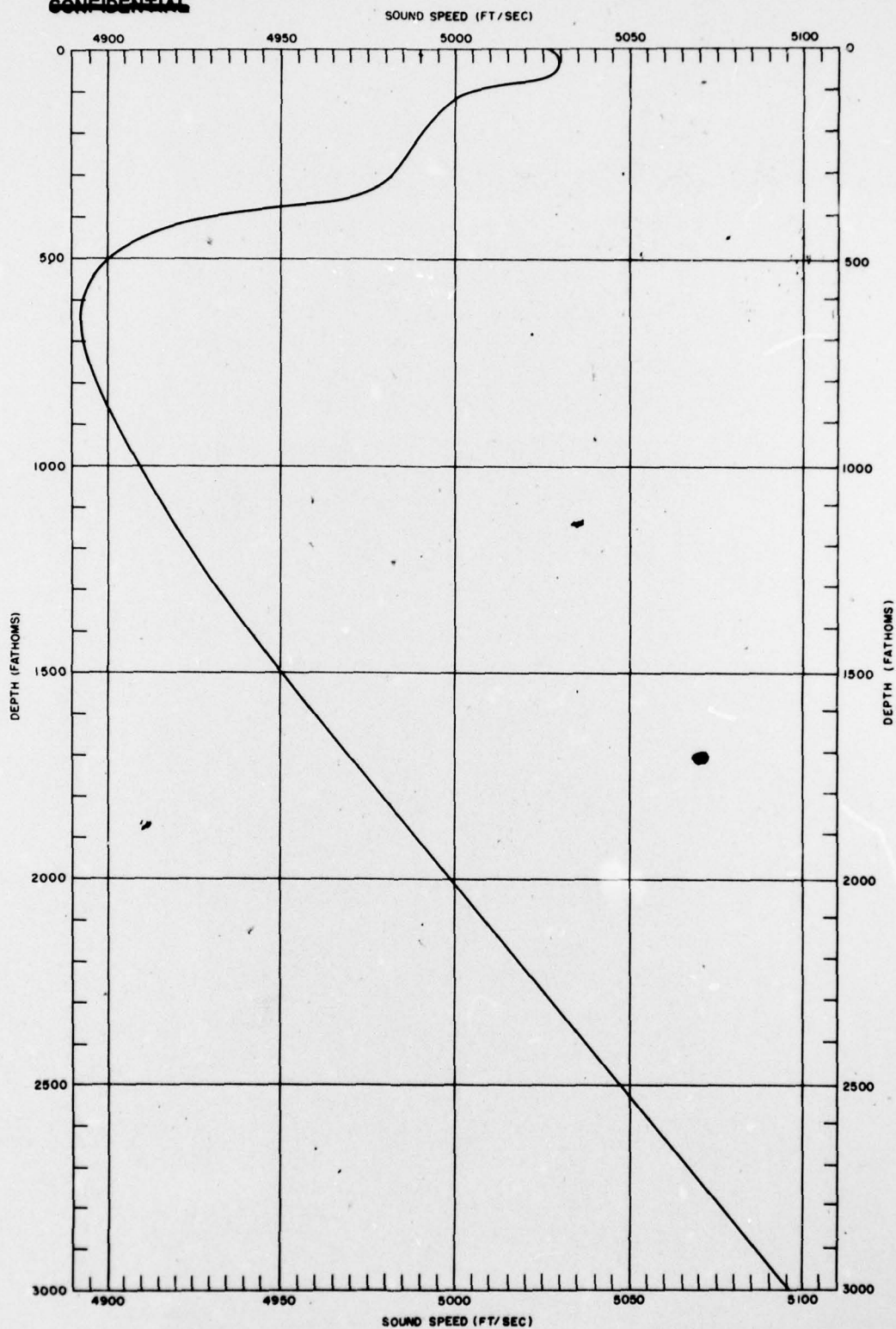


FIGURE 1 TYPICAL SOUND SPEED PROFILE FOR FEBRUARY

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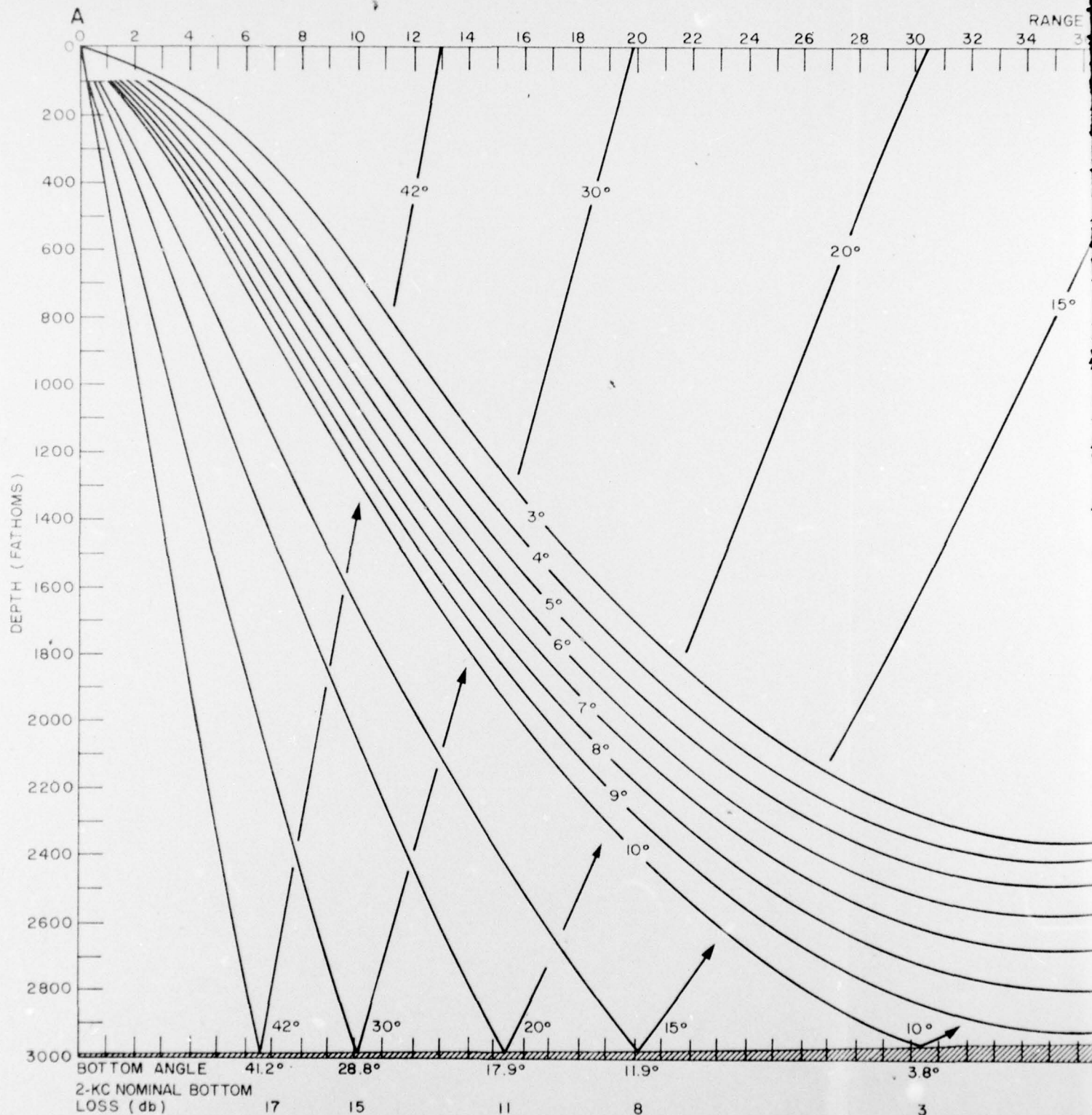
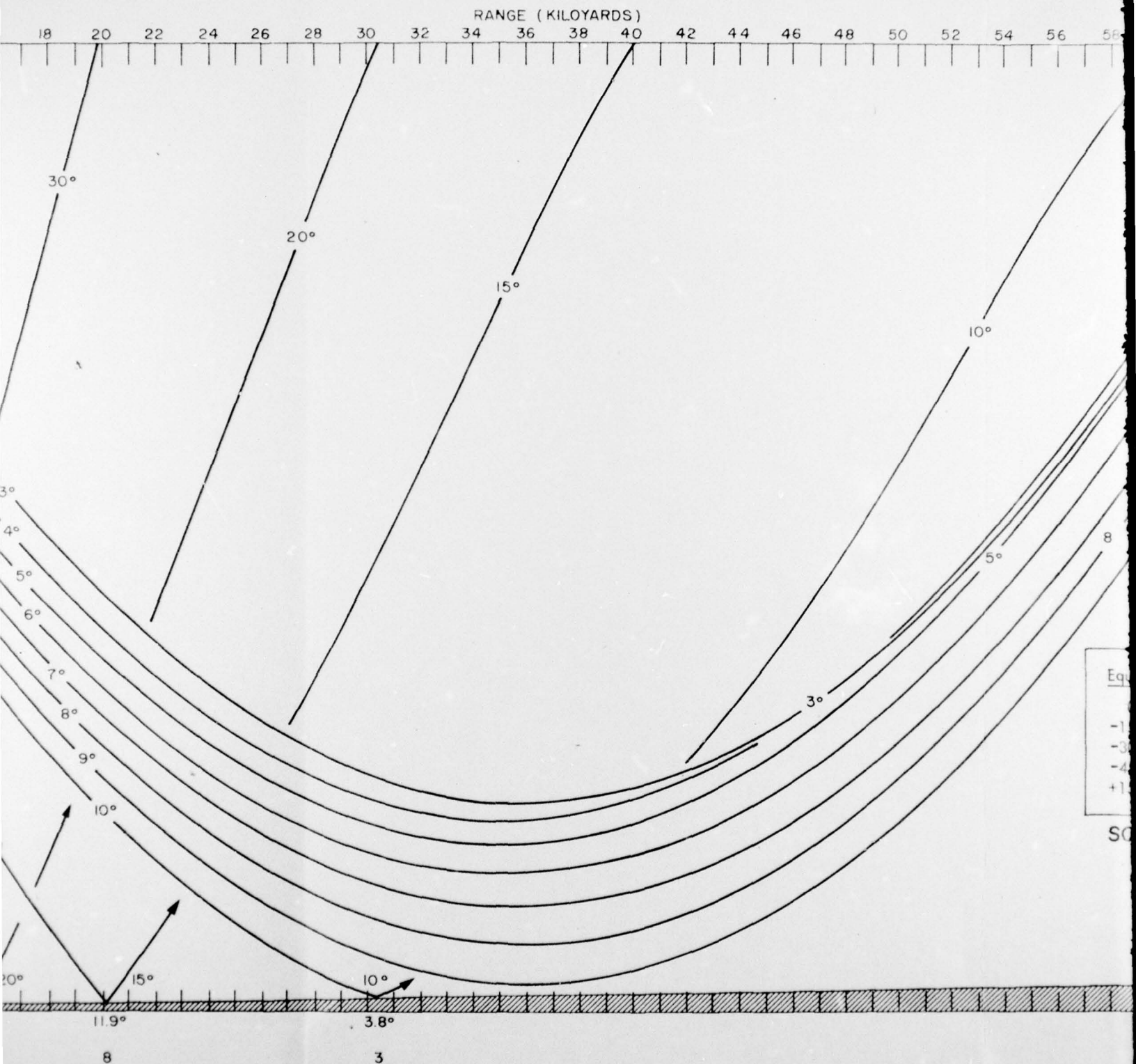
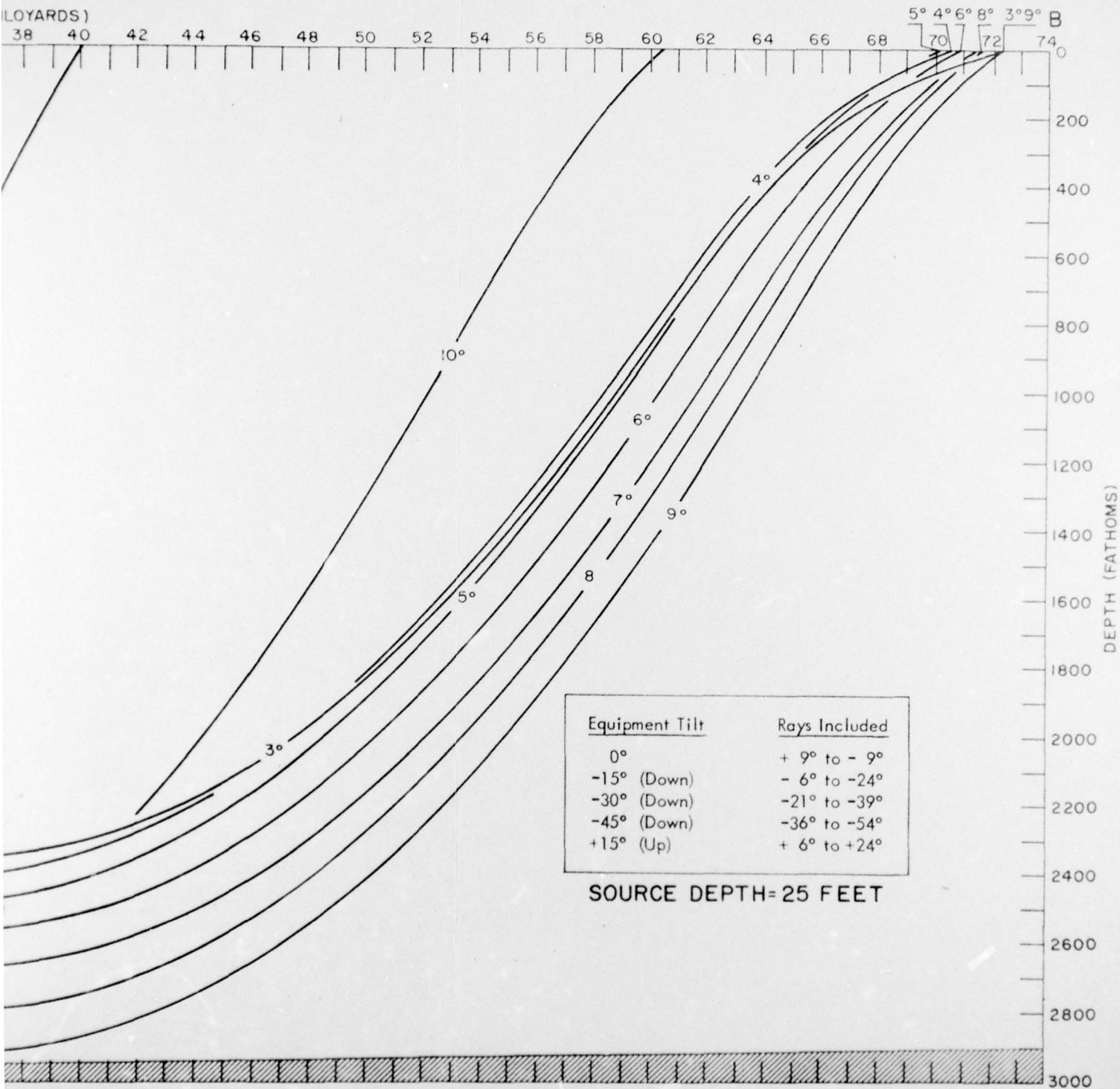


FIGURE 2 RAY DIAGRAM FOR FEBRUARY COMPUTED FROM TYPICAL



GRAM FOR FEBRUARY COMPUTED FROM TYPICAL SOUND SPEED PROFILE FOR CROSS SECTION A-B S

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SOUND SPEED PROFILE FOR CROSS SECTION A-B SHOWN ON FIGURE 4

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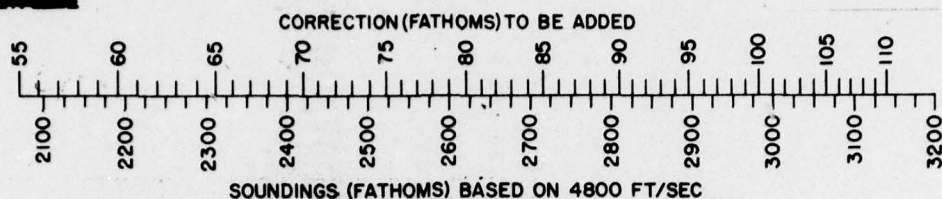


FIGURE 3 CORRECTION TO ECHO-SOUNDER DEPTH TO OBTAIN TRUE DEPTH FOR FEBRUARY

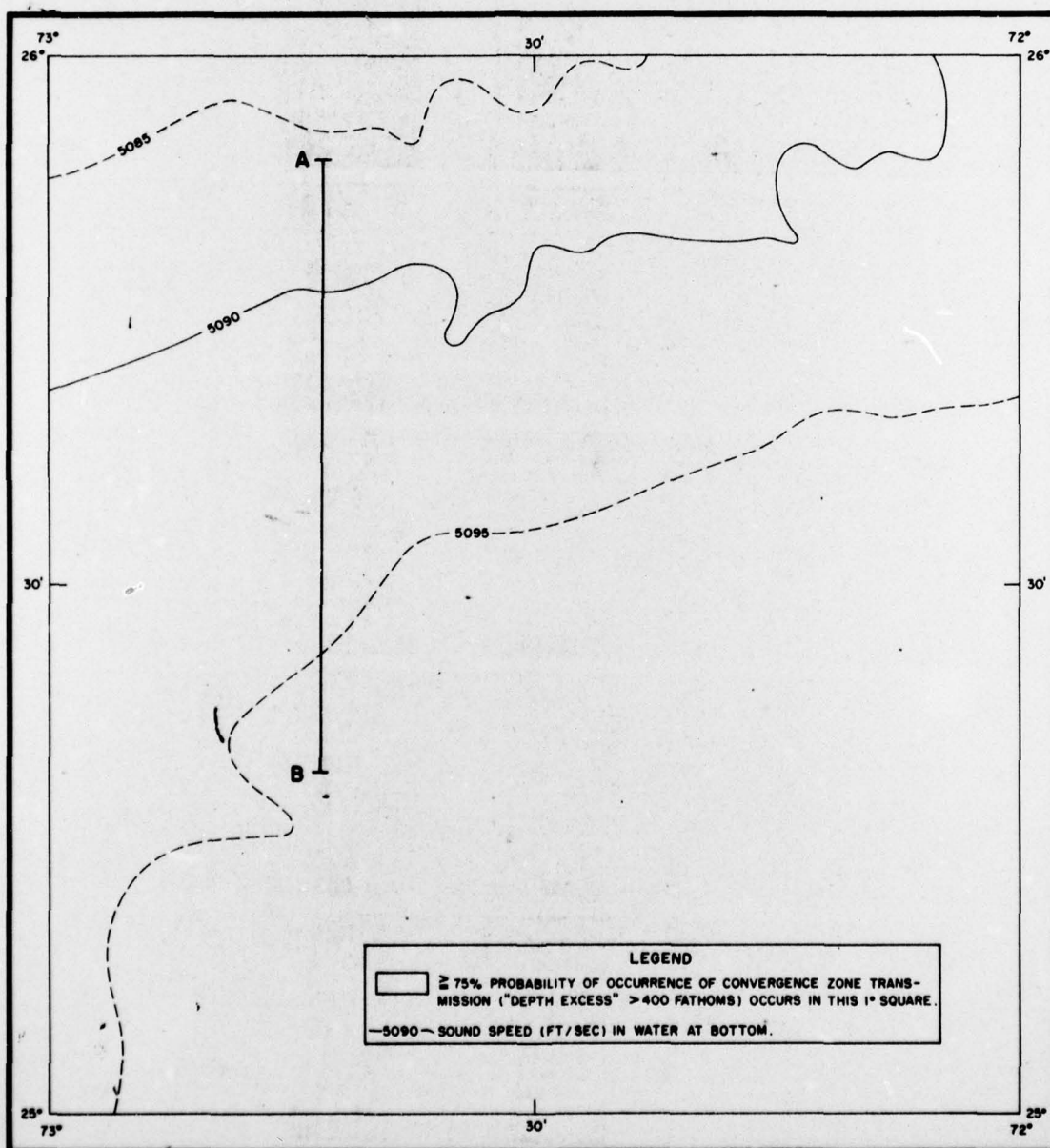
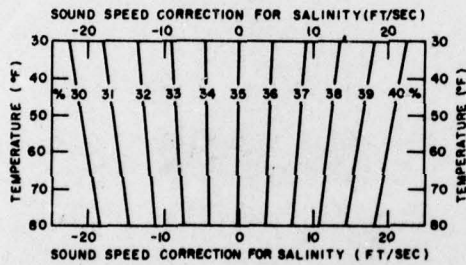
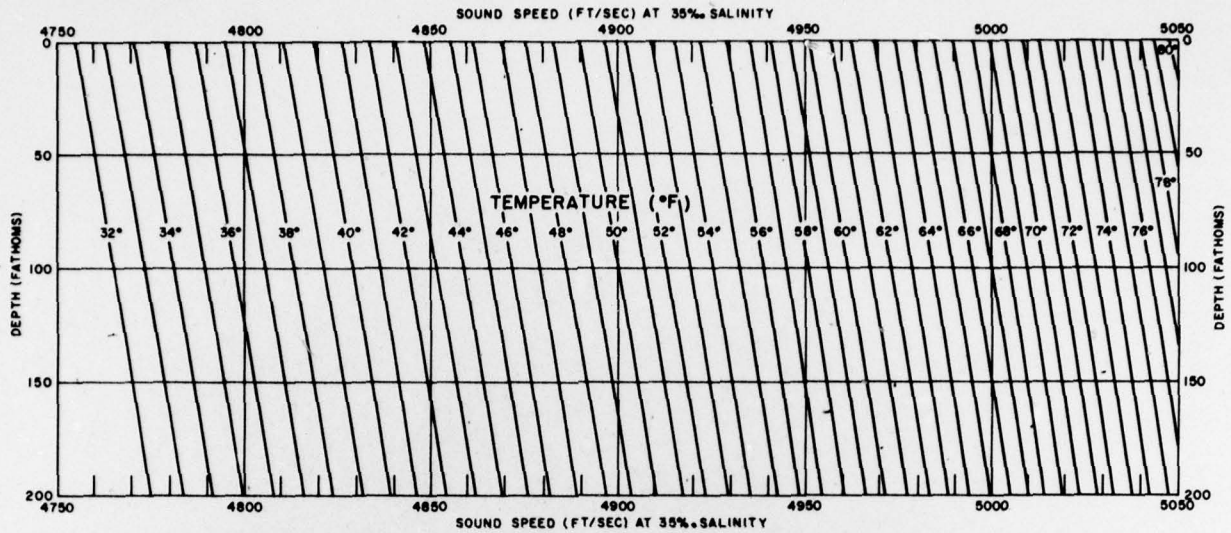


FIGURE 4 SOUND SPEED (FT/SEC) IN WATER AT BOTTOM AND CONVERGENCE ZONE PROBABILITY OF OCCURRENCE

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NORMAL SALINITY CORRECTION
FOR THIS AREA AND SEASON
IS + 4 FT/SEC

FIGURE 5 SOUND SPEED NOMOGRAM

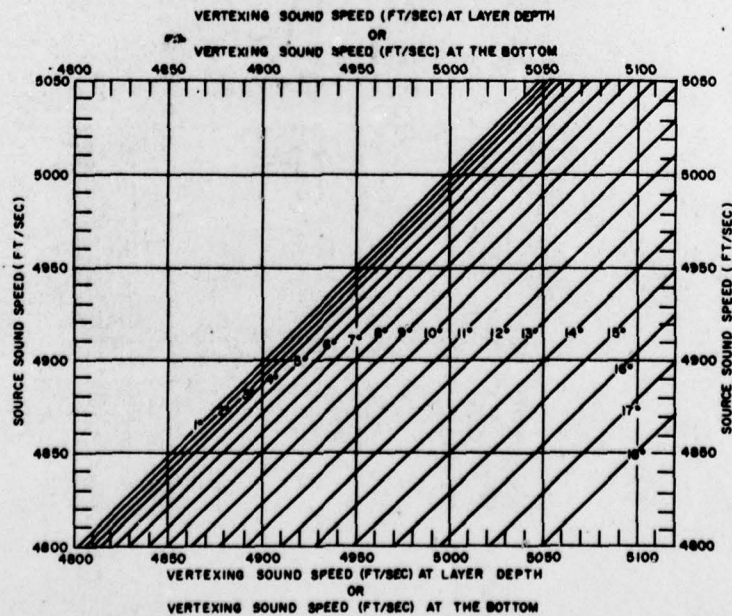


FIGURE 6 INCLINATION ANGLE VS SOURCE SOUND SPEED AND VERTEXING
SOUND SPEED

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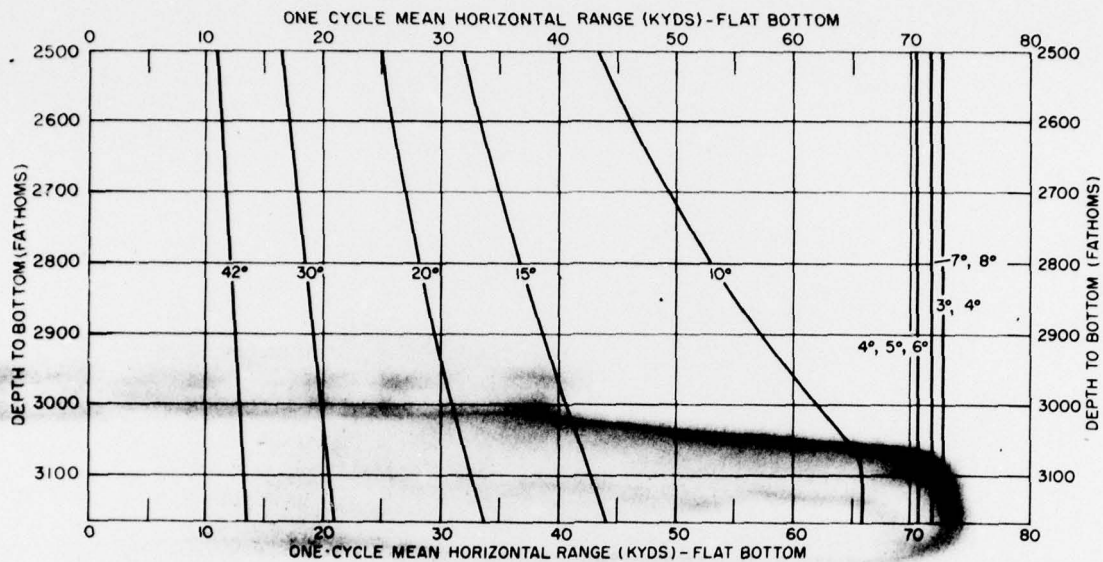


FIGURE 7 MEAN HORIZONTAL RANGE VS INITIAL ANGLE AND WATER DEPTH FOR FEBRUARY

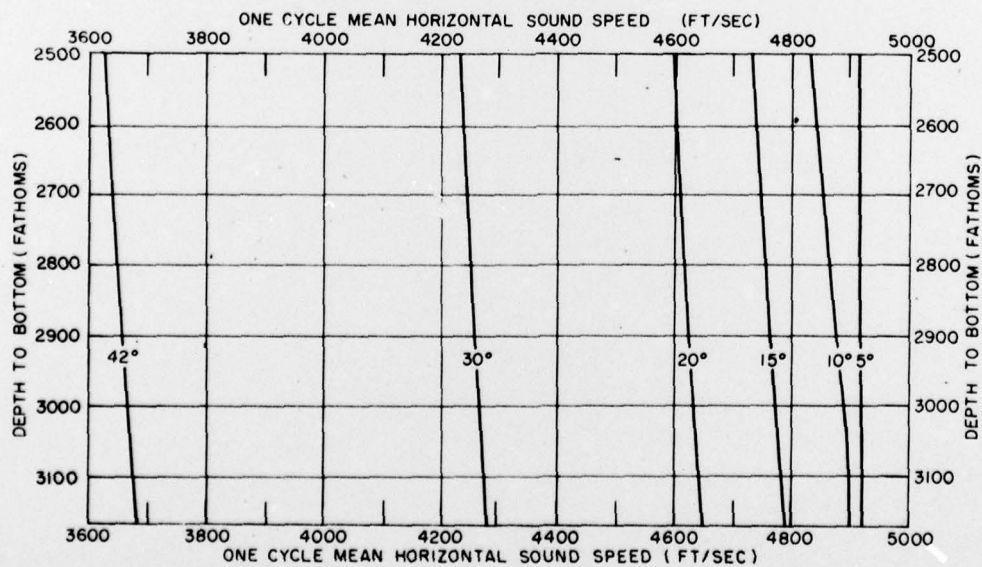


FIGURE 8 MEAN HORIZONTAL SOUND SPEED VS INITIAL ANGLE AND WATER DEPTH FOR FEBRUARY

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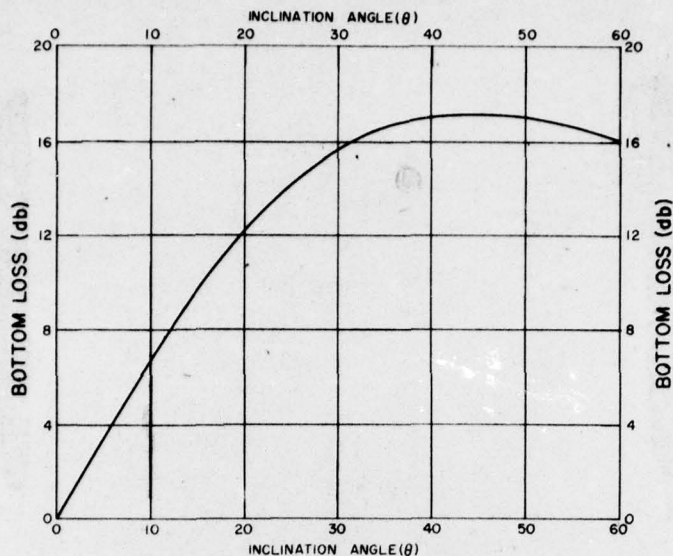


FIGURE 9 NOMINAL BOTTOM LOSS

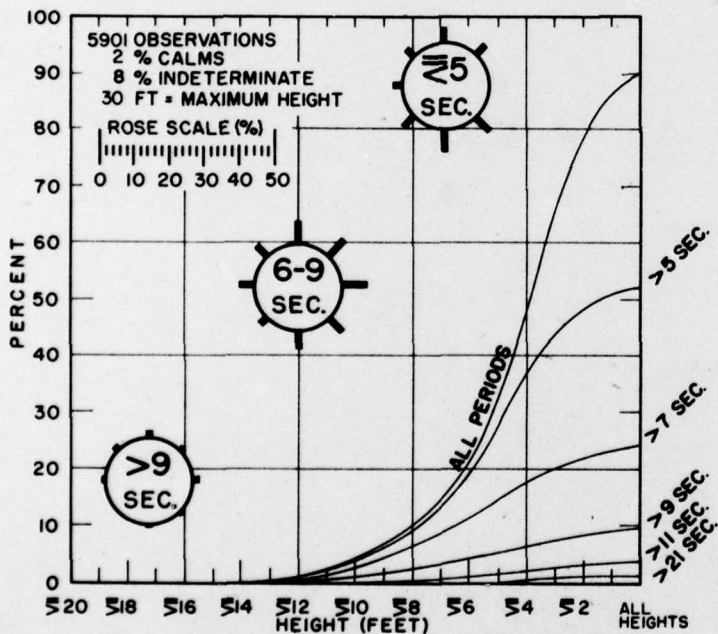
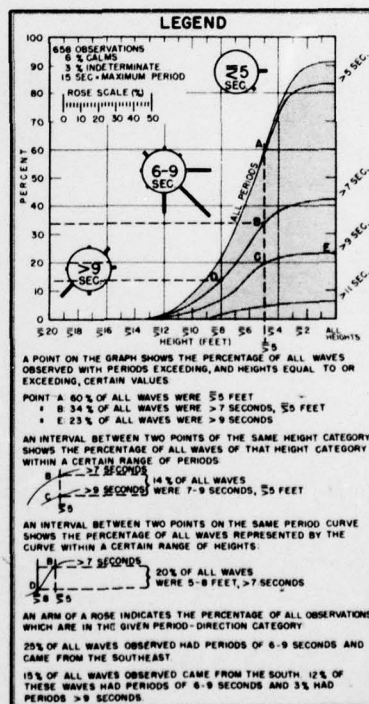


FIGURE 10 WAVES FOR JANUARY, FEBRUARY, AND MARCH
AREA (24°-26°N, 72°-74°W)



SEA CODE	0	1	2	3	4	5	6	7	8	9	TOTAL OBS
SEA HEIGHT (FT)	CALM	<1	1-3	3-5	5-8	8-12	12-20	20-40	540	CONFUSED	
PERCENT	1.2	14.9	31.7	39.1	8.7	3.7	0.6	-	-	-	161

SEA TABULATIONS IN PERCENT OF OBSERVATIONS FOR FEBRUARY
AREA (24°-26°N, 72°-74°W)

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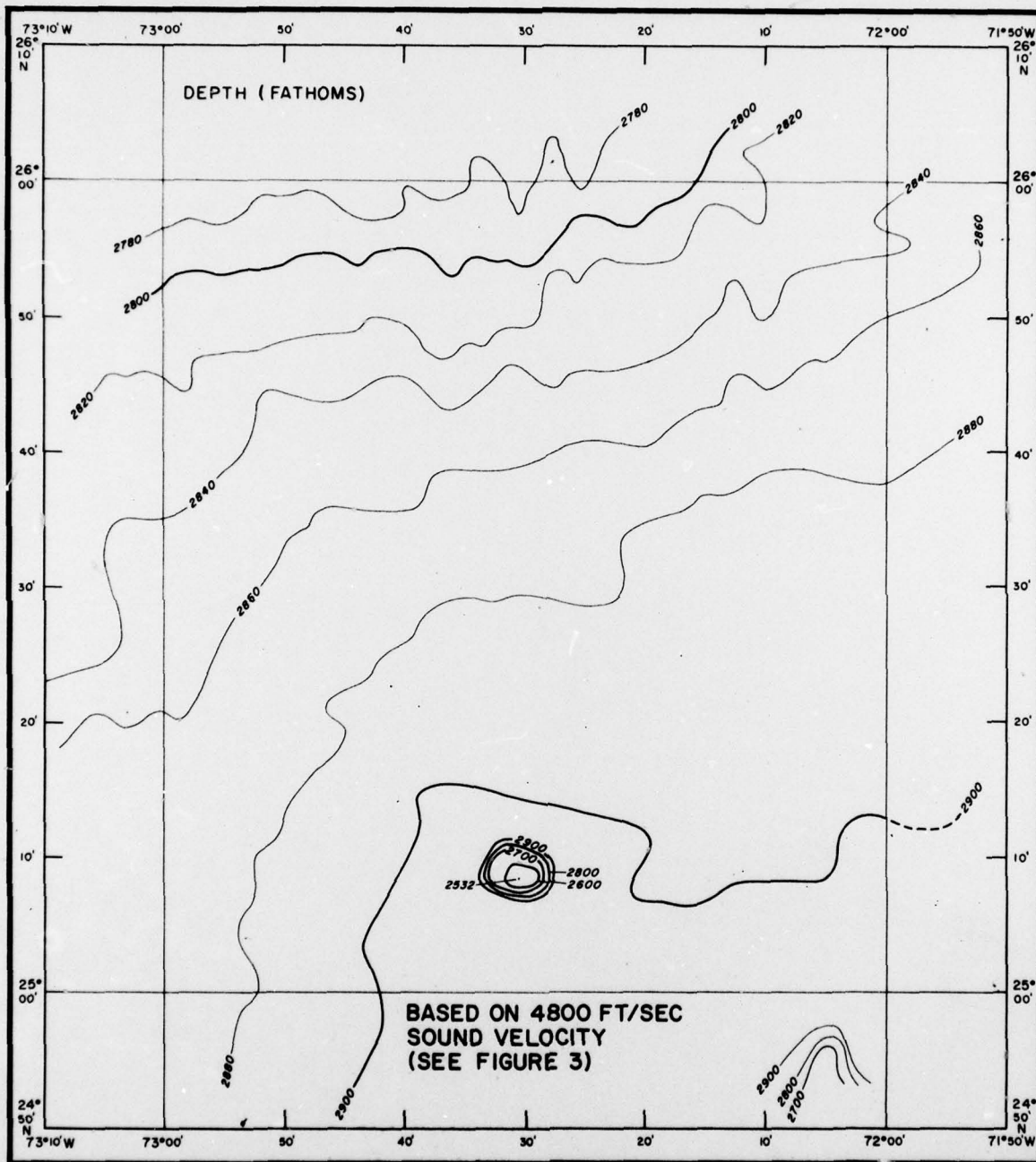


FIGURE 12 BATHYMETRY

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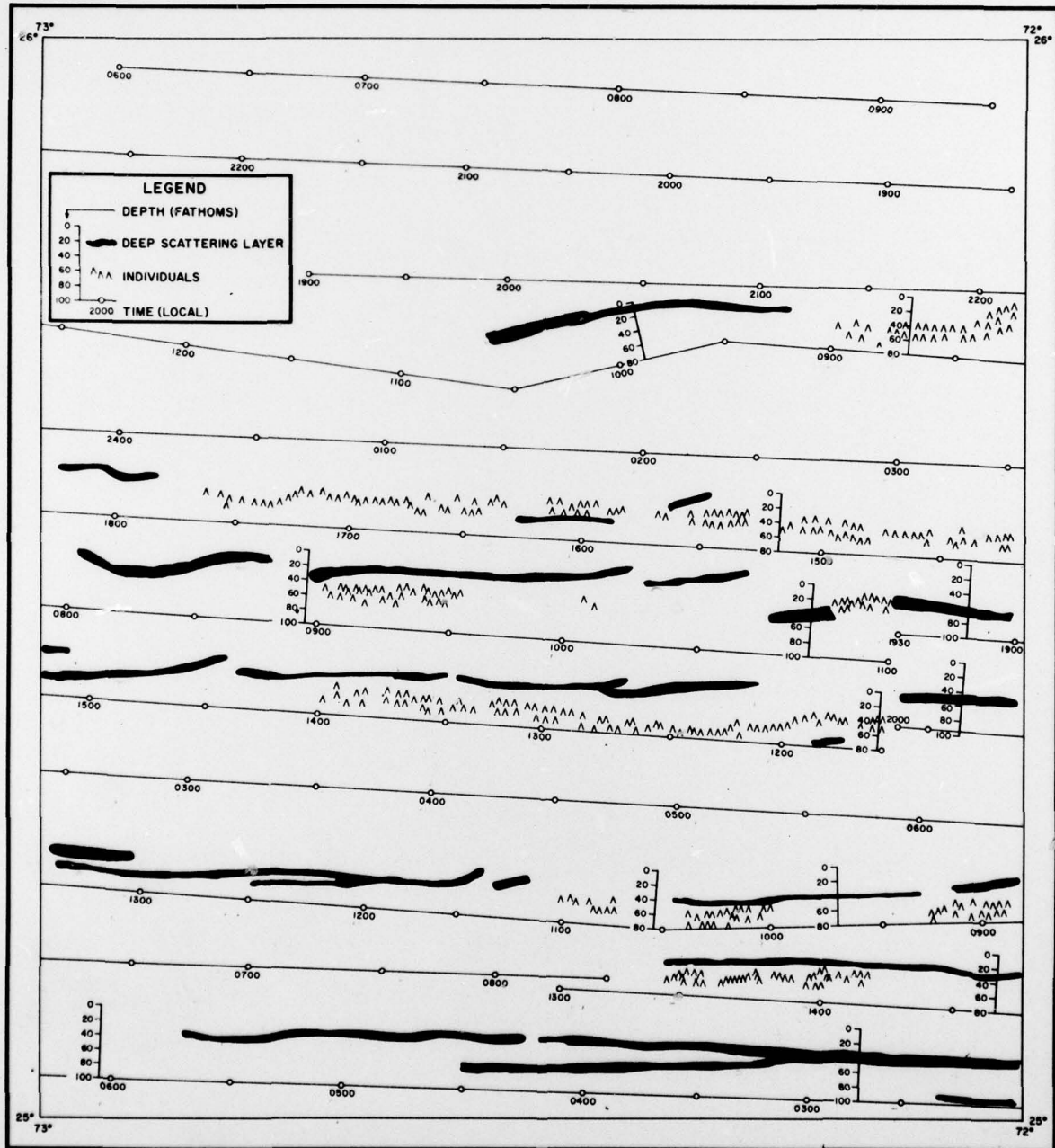


FIGURE 13 SCATTERING LAYER FOR FEBRUARY

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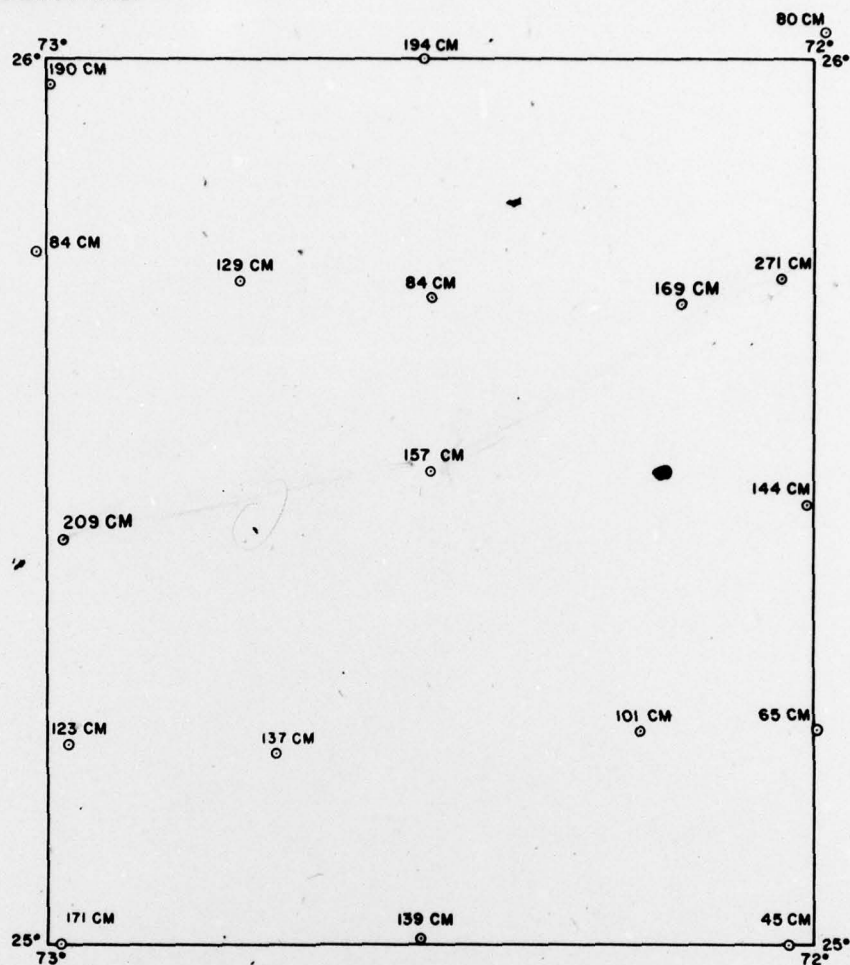


FIGURE 14 BOTTOM CORE LOCATIONS AND LENGTH OF CORE OBTAINED

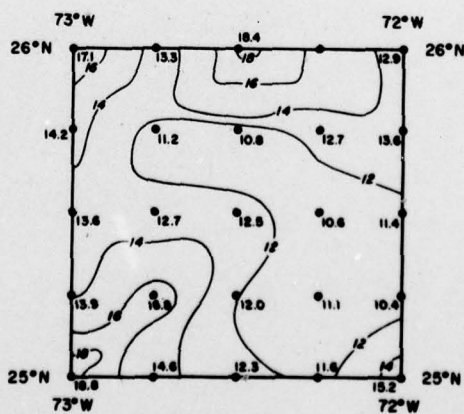


FIGURE 15 12-KC NORMAL INCIDENCE BOTTOM LOSS MEASUREMENTS IN db

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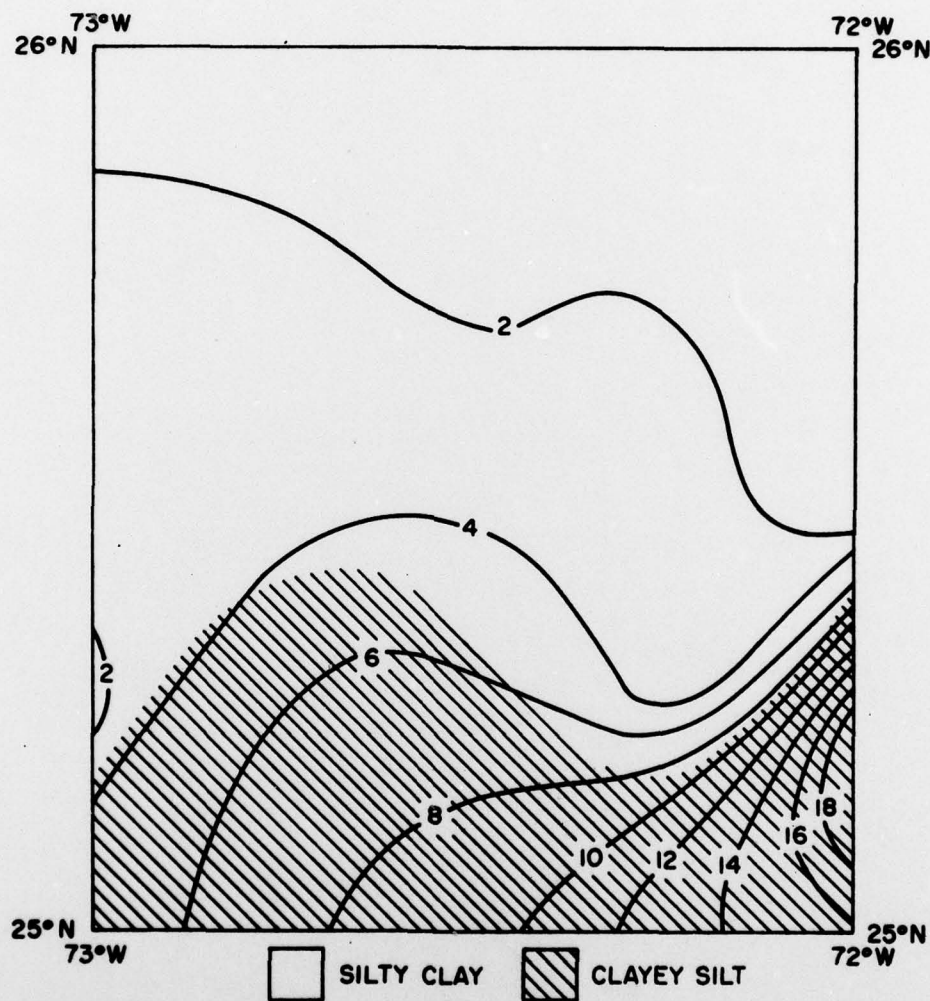


FIGURE 16 SURFACE SEDIMENT TYPE AND MEDIAN DIAMETER (MICRONS)

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BOTTOM TOPOGRAPHY

The area is situated on the southwest edge of the Hatteras Abyssal Plain where the ocean bottom is flat with a slope of less than 1:1000. Depths in this area range from 2,780 to greater than 2,900 fathoms with a seamount on the southern edge rising to a depth of 2,532 fathoms. Bottom profiles were constructed from data from the USS RHODES in 1961.

The depth profiles, which were recorded in an east-west direction, indicate slope gradients of less than 1 degree. This was determined by generalizing the slopes of several randomly selected profiles. The seamount in the vicinity of 25°07'N, 73°30'W has a slope of greater than 2 degrees. No gradients were determined in the north-south direction because the positions could not be repeated with sufficient precision.

Positions of this survey were obtained with Loran A. These positions have been corrected and adjusted to give a best fit. Position errors average 3 miles, and vary between 1 and 7 miles.

DEEP SCATTERING LAYER (DSL)

The deep scattering layer and the individual scatterers were recorded on a precision depth recorder (PDR) using a 3 to 5 millisecond pulse length. The scattering layers are rather shallow and at varying depths; thus, it is difficult to determine a pattern of depth, ascension, or descension.

BIOLOGY

During February there is probably less than one whale per 1,000 square miles. Some whale sharks (to 45 feet long) and bluefin tunas (to 10 feet long) may be present, but their concentration is unknown.

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BOTTOM ACOUSTIC PROPERTIES

The cores taken in this area vary in length to a maximum of almost 9 feet and consisted of yellow brown clay interbedded with distinct thin layers of silt and, in some instances, very thin sand layers. The high porosity (70 to 80 %), low density, and fine-grained clay sediment present in this area indicates possible low velocity sediments having a low acoustic impedance. However, increased grain size and density and decreased porosity in the silt layers indicates an increase in the acoustic impedance of these layers. The presence of low velocity and low acoustic impedance sediments generally provides poor reflectivity; however, the presence of silt and sand layers in the short cores and the possible presence of additional silt and sand layers, known to occur in abyssal plain regions, indicates that this area could provide good reflectivity.

The normal incidence 12-kc reflection loss ranges from a low of 10 db to a high of 18 db and shows that anomalously high losses are not found at this high frequency and grazing angle. Assuming that reflection loss decreases with decreasing frequency and grazing angle it would appear, on the basis of 12-kc normal incidence reflection loss and from the core analysis as well as from the accessibility of the area to turbidity currents, that this area would be one of good reflectivity.

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